

Noisy Uncertainty: Chapter 2

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I. Preliminaries

The Challenge: How could you (1) truly have exact¹ probabilities that (2) influence your actions without (3) being able to remove your higher-order uncertainty (**HOU**) by acting?

¹ Or relatively exact

Internalist, behavioralist impulses.

Subjective vs. rational vs. objective probabilities.

Standard operationalization of subjective probabilities: betting.

But then just see what you want to pay for a bet!

↪ So most people working on higher-order uncertainty focus on *rational* probabilities.

How much willing to pay for a bet $B = \$1$ if heads, $\$0$ if tails?

$P(q) = 0.5 \rightsquigarrow \0.50

$P(q) = 0.7 \rightsquigarrow \0.70

$P(q) = 0.2 \rightsquigarrow \0.20

E.g. Williamson 2000, 2008; Elga 2013; Lasonen-Aarnio 2015; Salow 2018; Hedden 2019; Dorst 2020; Gallow 2021; Das 2022, etc.

Basic idea:

If you have subjective probabilities, then there are facts about what they are at a given time. They can be objects of uncertainty.

At least for others.

You do have some higher-order opinions about your own opinions.

at least 1 spoon?

(?)⇒ To avoid HOU, must be HO *certain* (**HOC**).

Cognitive noise = randomness between mental state and its effects. Can make mental state difficult to discern.

Example(?): stress vs. dehydration.

Internalist objection: that's uncertainty about the *cause* of the mental state, not the state itself.

Alternatives? Maybe:

1) Appearance of tree's height.

2) Strongest belief about height.

3) How many cookies you want.

4) Which image is clearer (eye doctor).

...

Likewise, maybe: knowing algorithmic level is noisy can affect whether computational level is HOC or HOU.

II. Sampling model (Urns in the head)

Sampling is *algorithmic* level, not computational, in Marr's levels.

Levels can interact (e.g. resource constraints; algorithmic complexity).

Generative models; sampling propensities; elicitations.

Spoon + cereal model.

Vectors as probabilities;

$P = (0.35, 0.15, 0.20, 0.30)$ vs

$\epsilon = (0.27, 0.18, 0.18, 0.36)$

Sampling View of Credences: Your credence in q at time t is the sampling propensity of your generative model to generate q -samples at t .

Separate (1) thing that directly encodes/updates beliefs (credences) from (2) thing that directly interfaces with action (elicitations).

Theoretical evidence: this is how computer scientists have to do it.

Empirical evidence.

- Generative models: intuitive physics and social reasoning

- Probability-matching, 3-cup task, sigmoid response rates.

Example: hard-to-discern generative model. Can condition it.
Precise sampling propensities, but samples always noisy.

Q: Does this match the philosophers' notion of credences?

III. Sampling and *higher-order* uncertainty

How represent that uncertainty explicitly?

Third-person case: they have a distribution over both a 'first-order' question (d or $\neg d$) and a 'second-order' one ($P(d) = 0.55$ or $P(d) = 0.45$).
→ E.g. Stan: (0.45, 0.15, 0.10, 0.30) over $(d_h, \bar{d}_h, d_l, \bar{d}_l)$.
Encoded in sampling propensities.

If he observes you elicit your credence by guessing, then he can update on that to get (inconclusive) evidence about what your credences were.

First-person case: What about the *higher-order* case, where you're uncertain about *your own* sampling propensities? I.e. your sampling propensities are uncertain about themselves.

Claim: works the same way. Nothing mysterious.

Updating on your own elicitations still fails to eliminate HOU.

IV. Noisy sampling requires HOU

Standard view: sampling explains ambiguous judgments, not clear ones.

But there's a continuum: Maggie- n cases.

Sampling model explains this, once we use your HO opinions.

Argument:

(P1) Sampling: (If sampling model is right, then) if $P(p) = y$, then if you draw a sample about p it's y -likely to be a p -sample.

(P2) Mean elicitations: (If sampling model is right, then) an available strategy for estimating the value of a variable X is to elicit samples and then report the mean value of X amongst those samples.

Conclusion: If sampling model is right, then: if noise is inevitable and you have HO opinions, you must have higher-order uncertainty.

Worries:

W1: Sub-personal models with no higher-order opinions?

W2: Why doesn't this imply (falsely) that we should be able to noiselessly sample from the distributions in our computers?

More generally, it'll be over a 'P-closed' subject-matter \mathcal{Q} , such that the answer to \mathcal{Q} also tells you what P 's credences are about \mathcal{Q} .

E.g. if know will draw 11 samples and guess most likely, $\text{Binomial}(11, P(d))$.
(If unsure, marginalize.)

Urn unsure about *its own contents*??

I suspect some self-knowledge people will be unhappy here...

Icard 2016, etc.

Outcome- vs. estimate-sampling.
Note: both can be seen as getting an elicited distribution ϵ , but then *doing* different things with it: calculating $\mathbb{E}_\epsilon(1_q)$ or $\mathbb{E}_\epsilon(P(q))$.

And since *reasonable* agents would avoid noise if they can: if reasonable agents have noise, they must have higher-order uncertainty

(?): No HO opinions. Or if they do, uncertain b/c logically non-omniscient.

W3: Sampling enough removes HOU.

Simulations and Experiment:

Simple idea. Not very diagnostic if succeeds, but *really bad* if it fails.

Simulations: random Ambiguous-Bayesian models [hang tight] with a random variable you have ambiguous estimate about; give Lo, Med, or Hi information about; elicit estimate-samples and track (1) mean elicited estimates and (2) within-agent noise in elicited estimate.

Experiment: Try to do the same thing with real people.

- Tell about WC tasks; repeatedly give scenarios where character X has seen n , and we're tallying how well they did. How many do you estimate they completed?
- 8 scenarios; 4 fillers; 4 targets that varied n and the character X , ($n = 100, 126, 72, 44$).
- Randomize clarity into Lo, Med, and Hi.
- Prediction 1: not much effect on mean estimates.
- Prediction 2: big effect on intra-personal noise in estimates.

Reply: That *changes* opinions (to informed probabilities).

Counter-reply: Only applies to computationally limited agents.

Counter-counter: Something about expanding π . Or about being unsure whether can do iid sampling. Or...

To force re-estimating

Lo: 0–100%; Med: 25–75%; Hi: 46–54%

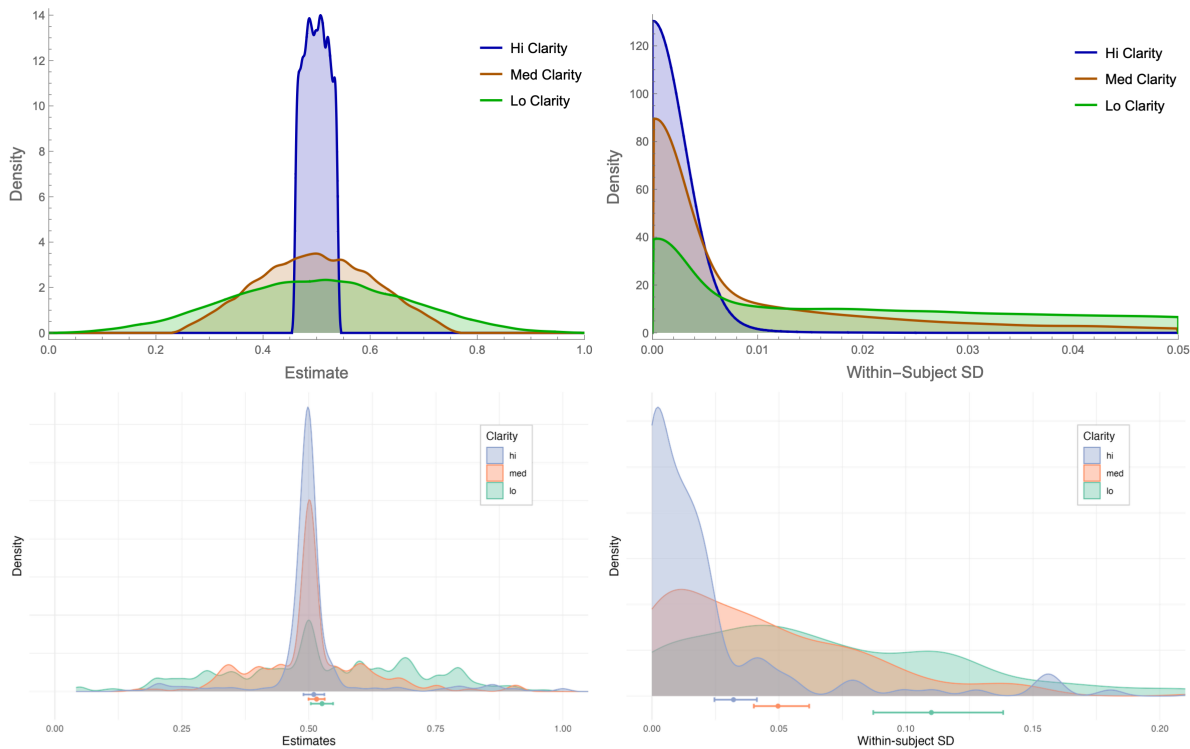


Figure 2.7: **Top:** Simulation results showing (left) individual estimates and (right) within-subject standard deviation in their estimates, divided by clarity. **Bottom:** Experimental results showing the same thing, along with Bayesian-regression estimates and 95%-credible intervals for the means below the x -axis.

V. Generalizing: Cognitive noise implies HOU

Easy to imagine alternatives; eg Gaussian noise in elicited x .

Argument 1: Timothy Williamson says so.

And hence so does Alex Byrne.

Argument 2:

(P1) Cognitive Noise: In estimating your credence in d under ambiguity (in normal conditions), if $P(d) = x$, then there's a $y > 0$ such that there's a decent ($\geq 20\%$) chance that you'll give an estimate for $P(d)$ that's either above $x + y$ or below $x - y$.

With \mathcal{E} a variable for your elicitation:
 $ch(\mathcal{E} < x - y \text{ or } \mathcal{E} > x + y) \geq 0.2$

(P2) Certainty Precludes Chance: In normal conditions, if you're certain that X is between x_1 and x_2 , then you can elicit an estimate for X in a way that has a high ($\geq 90\%$) chance of being b/t x_1 and x_2 .

Conclusion: If under normal conditions you have higher-order opinions and inevitably have (significant) noise in your estimate, then you have higher-order uncertainty.

Q: Every time I give this argument it feels too easy. Am I missing something?

Argument 3: Irrelevant influences on confidence rating (Matthias).

Worries:

W4: Imprecision? Bah!

W5: ??

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